Robust Bayesian Neural Networks by Spectral Expectation Bound Regularization

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- Bayesian neural networks have been widely used in many applications.
- Adversarial sensitivity is a common problem of deep neural network models, including Bayesian neural networks.
- Even though Bayesian neural networks have been found more robust to adversarial attacks, their ability to deal with adversarial noises in practice is still limited.

• It is proved that a Bayesian neural network model will become more robust if $\mathbb{E}||W||_2$ of each layer get restricted.

Theorem

Consider function $f_W(\mathbf{x}) = f(W\mathbf{x} + \mathbf{b})$, where the activation function $f(\cdot)$ is Lipschitz continuous with Lipschitz constant Lip(f). For any perturbation $\boldsymbol{\xi}$ with norm $\|\boldsymbol{\xi}\|$, we have

$$\mathbb{E}_{\mathsf{W}} \| f_{\mathsf{W}}(\mathbf{x} + \boldsymbol{\xi}) - f_{\mathsf{W}}(\mathbf{x}) \| \le Lip(f) \cdot \mathbb{E} \| W \|_2 \cdot \| \boldsymbol{\xi} \|, \tag{1}$$

where $\|W\|_2$ represents the spectral norm of matrix W, and it is defined as

$$\|W\|_{2} = \max_{\boldsymbol{\xi} \in \mathbb{R}^{n}, \boldsymbol{\xi} \neq 0} \frac{\|W\boldsymbol{\xi}\|}{\|\boldsymbol{\xi}\|}.$$
 (2)

How to restrict $\mathbb{E} ||W||_2$ in practice? A naive method:

$$\underset{W}{\text{minimize}} \quad \mathcal{L} + \frac{\lambda}{2} \sum_{l=1}^{L} (\mathbb{E} \| W^{l} \|_{2})^{2}, \tag{3}$$

The expectation is estimated by **Monte Carlo sampling** (K times). The spectral norm is calculated by **Power Iteration** (N iterations) method.

The time complexity is O(KN).

A substitution: Estimation of its **upper bound**.

Theorem

Consider a Gaussian random matrix $W \in \mathbb{R}^{m \times n}$, where $W_{ij} \sim N(M_{ij}, A_{ij}^2)$ with $M, A \in \mathbb{R}^{m \times n}$. Suppose $G \in \mathbb{R}^{m \times n}$ is a zero-mean Gaussian random matrix with the same variance, i.e., $G_{ij} \sim N(0, A_{ij}^2)$. We have

$$\mathbb{E}\|W\|_{2} \leq \|M\|_{2} + c\left(\max_{i}\|A_{i,:}\| + \max_{j}\|A_{:,j}\| + \mathbb{E}\max_{i,j}|G_{ij}|\right), \quad (4)$$

where c is a constant independent of W.

The estimation of the upper bound is faster: O(K + N)

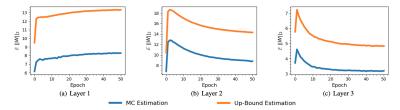
Denote \mathcal{L}_S as half of the square of the upper bound of $\mathbb{E} ||W||_2$ in each layer. Add it into the loss function:

$$\min_{\mathsf{W}} \mathsf{inimize} \ \mathcal{L} + \lambda \cdot \mathcal{L}_{\mathcal{S}}. \tag{5}$$

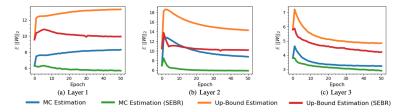
The method is named as Spectral Expectation Bound Regularization (SEBR).

Verifications

• The upper bounds reflect the variation trends of real values accurately.



• The real values get decreased bacause of the usage of SEBR.



• The time costs get reduced compared with the naive method.

| Method | Avg. time per epoch |
|------------------------------|---------------------|
| Reg. on $\mathbb{E} \ W\ _2$ | 1654.8 (s) |
| SEBR | 410.5 (s) |

Table 1. Time cost comparison between SEBR and the direct regularization on $\mathbb{E}||W||_2$.

The epistemic uncertainty of the model output gets reduced by SEBR:

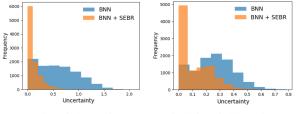
Theorem

Consider a Bayesian neural network with only a linear layer $f_W(\mathbf{x}) = W\mathbf{x} + \mathbf{b}$, where $\mathbf{x} \in \mathbb{R}^n$, $W \in \mathbb{R}^{m \times n}$. Denote the epistemic uncertainty of the output after one step gradient descent without SEBR as H_e , and the epistemic uncertainty after one step gradient descent with SEBR as H'_e . With sufficient sample times, we have

$$H'_e \le H_e. \tag{6}$$

It verifies the robustness of the model from another point of view.

Experiments on the verification of the decrease of the output uncertainty.





(b) Epistemic Uncertainty

Figure 4. Uncertainties measured by Bayesian neural networks on data with adversarial noises. Models trained with SEBR have lower uncertainty on the predictions. *Best viewed in color.*

Experiments on multiple structures (i.e., MLP and CNN), multiple datasets (MNIST and Fashion-MNIST), and multiple attacks (i.e., FGSM and PGD) verify the efficiency of the proposed method.

| Model | Dataset | Attack | Noise | ℓ_∞ norm | Acc. w/o. SEBR (%) | Acc. w. SEBR (%) | Δ Avg. Improv. (%) |
|-----------------|------------------|--------|--------|--------------------|--------------------|-------------------|---------------------------|
| Bayesian MLP | MNIST | / | 0 | 0 | 97.05 ± 0.38 | 96.83 ± 0.48 | -0.22 |
| | | FGSM | small | 0.04 | 83.83 ± 0.51 | 85.74 ± 0.64 | + 1.91 |
| | | | medium | 0.16 | 8.97 ± 0.28 | 43.69 ± 5.92 | + 34.72 |
| | | | large | 0.3 | 5.06 ± 0.21 | 24.54 ± 8.65 | + 19.48 |
| | | PGD | small | 0.04 | 81.99 ± 1.05 | 83.67 ± 0.67 | + 1.68 |
| | | | medium | 0.16 | 4.20 ± 0.84 | 9.54 ± 2.82 | + 5.34 |
| | | | large | 0.22 | 1.55 ± 0.35 | 3.18 ± 1.52 | + 1.63 |
| Bayesian CNN | MNIST | / | 0 | 0 | 98.88 ± 0.27 | 98.70 ± 0.04 | -0.18 |
| | | FGSM | small | 0.04 | 85.64 ± 2.52 | 86.14 ± 2.76 | + 0.50 |
| | | | medium | 0.08 | 55.98 ± 4.40 | 60.27 ± 8.65 | + 4.29 |
| | | | large | 0.14 | 18.16 ± 0.57 | 22.55 ± 11.23 | + 4.39 |
| | | PGD | small | 0.04 | 82.91 ± 2.63 | 85.10 ± 2.96 | + 2.19 |
| | | | medium | 0.08 | 36.53 ± 5.85 | 49.20 ± 10.75 | + 12.67 |
| | | | large | 0.14 | 9.88 ± 2.02 | 12.33 ± 5.31 | + 2.45 |
| Bayesian MLP | Fashion MNIST | / | 0 | 0 | 84.38 ± 0.37 | 78.75 ± 0.83 | -5.63 |
| | | FGSM | small | 0.04 | 60.96 ± 0.24 | 62.06 ± 1.15 | + 1.10 |
| | | | medium | 0.1 | 24.29 ± 1.16 | 31.65 ± 1.25 | + 7.36 |
| | | | large | 0.2 | 1.99 ± 0.57 | 4.59 ± 0.75 | + 2.60 |
| | | PGD | small | 0.04 | 59.86 ± 0.34 | 61.80 ± 1.13 | + 1.94 |
| | | | medium | 0.1 | 19.18 ± 1.01 | 29.67 ± 1.22 | + 10.49 |
| | | | large | 0.2 | 0.44 ± 0.14 | 2.71 ± 0.60 | + 2.27 |
| Bayesian CNN | Fashion MNIST | 1 | 0 | 0 | 87.45 ± 0.57 | 84.83 ± 0.33 | -2.62 |
| | | FGSM | small | 0.04 | 40.82 ± 1.86 | 46.03 ± 4.22 | + 5.21 |
| | | | medium | 0.08 | 15.89 ± 0.97 | 18.96 ± 5.00 | + 3.07 |
| | | | large | 0.1 | 10.24 ± 0.31 | 11.97 ± 3.95 | + 1.73 |
| | | PGD | small | 0.04 | 32.81 ± 1.70 | 39.92 ± 3.25 | + 7.11 |
| | | | medium | 0.06 | 15.03 ± 2.03 | 20.87 ± 4.00 | + 5.84 |
| | | | large | 0.08 | 5.62 ± 0.73 | 9.27 ± 1.62 | + 3.65 |

Table 2. Comparison on the Robustness of Models without SEBR and with SEBR. The mean value and maximum deviation of three runs are reported.

Experiments on more complex structure (i.e., VGG), more complex datasets (CIFAR-10/100) further verify the efficiency of the proposed method.

| Dataset | Attack | noise ℓ_∞ | w/o. SEBR | w. SEBR |
|----------|--------|---------------------|-----------|---------|
| | / | 0 | 91.65 | 92.09 |
| CIFAR10 | FGSM | 0.005 | 58.65 | 65.74 |
| | | 0.01 | 42.70 | 54.78 |
| | | 0.02 | 32.73 | 43.76 |
| | PGD | 0.005 | 46.33 | 50.40 |
| | | 0.01 | 9.73 | 16.11 |
| | | 0.02 | 2.31 | 2.95 |
| | / | 0 | 66.94 | 66.56 |
| | | 0.002 | 45.96 | 47.67 |
| | FGSM | 0.01 | 17.08 | 21.18 |
| CIFAR100 | | 0.02 | 12.52 | 15.97 |
| | PGD | 0.002 | 44.72 | 46.85 |
| | | 0.01 | 2.91 | 5.04 |
| | | 0.02 | 0.95 | 1.95 |

Table S1. Experiments on Bayesian CNN with VGG architecture.

Thanks!